


# DRAT-based Bit-Vector Proofs in CVC4<sup>\*</sup>

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**Abstract.** Many state-of-the-art Satisfiability Modulo Theories (SMT) solvers for the theory of fixed-size bit-vectors employ an approach called bit-blasting, where a given formula is translated into a Boolean satisfiability (SAT) problem and delegated to a SAT solver. Consequently, producing bit-vector proofs in an SMT solver requires incorporating SAT proofs into its proof infrastructure. In this paper, we describe three approaches for integrating DRAT proofs generated by an off-the-shelf SAT solver into the proof infrastructure of the SMT solver CVC4 and explore their strengths and weaknesses. We implemented all three approaches using CryptoMiniSat as the SAT back-end for its bit-blasting engine and evaluated performance in terms of proof-production and proof-checking.

## 1 Introduction

The majority of Satisfiability Modulo Theories (SMT) solvers for the theory of fixed-size bit-vectors employ an approach called bit-blasting. That is, an input formula is first simplified, and then eagerly translated into propositional logic and handed to a Boolean satisfiability (SAT) solver. Thus, when producing a proof of unsatisfiability for a given bit-vector input, it is crucial to obtain the unsatisfiability proof from the SAT solver back-end and incorporate it into a possibly larger SMT proof. The bit-blasting engine of the SMT solver CVC4 [1] currently supports several SAT solvers as back-ends. Producing proofs, however, is only supported with a modified version of MiniSat [6], which was extended to record resolution proofs that can be embedded into CVC4 proofs [9]. This custom MiniSat implementation requires extra maintenance and is less competitive than more recent off-the-shelf SAT solvers.

In recent years, the *Delete Resolution Asymmetric Tautologies* (DRAT) proof system [18], a generalization of *extended resolution* (ER) [17], has become the de facto standard for validating unsatisfiability in SAT solvers. Using a state-of-the-art SAT solver with support for DRAT inside CVC4 would allow CVC4 to use the latest, best SAT techniques while being able to produce bit-vector proofs without additional customization of the SAT solver code. However, in order to support this, CVC4 must be able to incorporate DRAT proofs into its proof infrastructure, which is based on LFSC, an extension of *Edinburgh's*

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*Logical Framework* [10] (LF) with functional programs called *side conditions* (see [15] for more details on LFSC and [2] for a more general survey of proofs in SMT-solvers). In this paper, we examine three approaches for translating DRAT proofs to LFSC: (i) a direct translation from DRAT to LFSC proofs, (ii) an intermediate translation from DRAT to Linear RAT (LRAT) proofs [4], and (iii) an intermediate translation from DRAT to ER proofs [11], which are then translated to LFSC. The produced proofs can be independently checked by any proof checker for LFSC. We describe the implementation of these three approaches for generating bit-vector proofs in CVC4, discuss their strengths and weaknesses, and evaluate their performance in terms of proof production and proof checking.

## 2 From DRAT to LFSC

We briefly review the definitions relevant to the proof systems DRAT, LRAT, and ER. More details can be found in [4,11,18].

A *literal* is either a propositional variable or its negation. A *clause* is a disjunction of literals, sometimes interpreted as a set of literals. A clause is *unit* if it is a singleton. A *formula* in conjunctive normal form (CNF) is a conjunction of clauses, sometimes interpreted as a set of clauses.

A proof for formula  $F$  in CNF is a sequence  $\pi = C_1, \dots, C_m, I_{m+1}, \dots, I_n$  with clauses  $C_1, \dots, C_m \in F$  and pairs  $I_i$  of the form  $\langle \diamond, X \rangle$ , where either  $\diamond \in \{a, d\}$  and  $X$  is a clause, or  $\diamond = e$  and  $X$  is a CNF formula. Letters  $a$ ,  $d$ , and  $e$  indicate addition, deletion, and extension, respectively. Sequence  $\pi$  induces a sequence of CNF formulas  $F_0, \dots, F_n$  such that  $F_i = \{C_1, \dots, C_i\}$  for  $1 \leq i \leq m$ , and for  $i > m$ ,  $F_i = F_{i-1} \cup \{C\}$  if  $I_i = \langle a, C \rangle$ ,  $F_i = F_{i-1} \setminus \{C\}$  if  $I_i = \langle d, C \rangle$ , and  $F_i = F_{i-1} \cup G$  if  $I_i = \langle e, G \rangle$ . It is a proof of unsatisfiability of  $F$  if  $\emptyset \in F_n$ .

A proof  $\pi$  of unsatisfiability of  $F$  is a valid ER proof if every  $I_i$  is either: (i)  $\langle a, C \cup D \rangle$ , where  $C \cup \{p\}$  and  $D \cup \{\bar{p}\} \in F_{i-1}$  for some  $p$ ; or (ii)  $\langle e, G \rangle$ , where  $G$  is the CNF translation of  $x \leftrightarrow \varphi$  with  $x$  a fresh variable and  $\varphi$  some formula over variables occurring in  $F_{i-1}$ . Proof  $\pi$  is a valid DRAT proof if every  $I_i$  is either  $\langle d, C \rangle$  or  $\langle a, C \rangle$  and for the latter, one of the following holds:

- $C$  is a *reverse unit propagation* (RUP) [8] in  $F_{i-1}$ , i.e., the empty clause is derivable from  $F_{i-1}$  and the negations of literals in  $C$  using unit propagation.
- $C$  is a *resolution asymmetric tautology* (RAT) in  $F_{i-1}$ , i.e., there is some  $p \in C$  such that for every  $D \cup \{\bar{p}\} \in F_{i-1}$ ,  $C \cup D$  is a RUP in  $F_{i-1}$ . If  $C$  is a RAT but not a RUP, we call it a *proper* RAT.

LRAT proofs are obtained from DRAT proofs by allowing a third element in each  $I_i$  that includes hints regarding the clauses and literals that are relevant for verifying the corresponding proof step.

### 2.1 Integration Methods

The *Logical Framework with Side Conditions* (LFSC) [15] is a statically and dependently typed Lisp-style meta language based on the Edinburgh Logical

```

(program is_specified_drat_proof ((f cnf) (proof DRATProof)) bool
  (match proof
    (DRATProofn (cnf_has_bottom f))
    ((DRATProofa c p) (
      match (is_rat f c) (tt (is_specified_drat_proof (cnfc c f) p)) (ff ff)))
    ((DRATProofd c p) (is_specified_drat_proof (cnf_remove_clause c f) p))))

```

**Fig. 1.** Side condition for checking a specified DRAT proof. The side conditions `cnf_has_bottom`, `is_rat`, and `cnf_remove_clause` are defined in the same signature. Type `cnfc` is a constructor for CNF formulas, and is defined in a separate signature.

Framework (LF) [10]. It can be used to define logical systems and check proofs written within them by way of the Curry-Howard correspondence. Like LF, LFSC is a framework in which axioms and derivation rules can be defined for multiple theories and their combination. LFSC additionally adds the notion of *side conditions* as functional programs, which can restrict the application of derivation rules. This is convenient for expressing proof-checking rules that are computational in nature. In order to use DRAT proofs in CVC4, the proofs need to be representable in LFSC. We consider the following three approaches for integrating DRAT proofs into LFSC.

**Checking DRAT Proofs in LFSC.** This approach directly translates DRAT proofs into LFSC. It requires creating a signature for DRAT in LFSC, which essentially is an LFSC implementation of a DRAT checker.

**Checking LRAT Proofs in LFSC.** LRAT proofs include hints to accelerate unit propagation while proof checking. We use the tool DRAT-trim [18] to translate DRAT proofs into the LRAT format and then check the resulting proof with an LRAT LFSC signature.

**Checking ER Proofs in LFSC.** This approach aims at further reducing computational overhead during proof checking by translating a DRAT proof into an ER proof with the tool `drat2er` [11]. The ER proof is then translated to LFSC and checked with an ER LFSC signature.

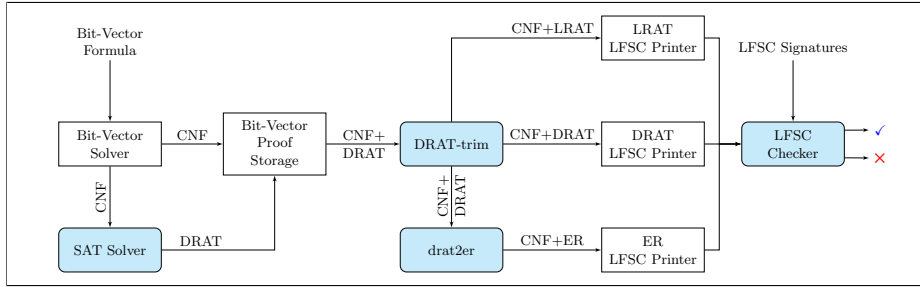
### 3 LFSC Signatures

In this section, we describe the main characteristics of the LFSC signatures<sup>1</sup> that we have defined for checking DRAT, LRAT, and ER proofs.

The *LFSC DRAT signature* makes extensive use of side conditions to express processes such as unit propagation and the search for the resolvents of a proper RAT. Because of the divergence between operational and specified DRAT and the resulting ambiguity (see [13] for further details), our signature accepts both kinds of proofs. Figure 1 shows the main side condition that is used to check a DRAT proof. Though we do not explain the LFSC syntax in detail here due to lack of space, the general idea can be easily understood. Given a proof candidate

<sup>1</sup> <https://github.com/CVC4/CVC4/blob/master/proofs/signatures/>





**Fig. 4.** Producing and checking LFSC proofs in DRAT, LRAT and ER proof systems in CVC4. White boxes are CVC4-internal components; blue boxes are external libraries.

solver, and optionally produce an LRAT proof that is forwarded to the LRAT LFSC pipeline. In case of DRAT LFSC proofs, we can directly use the optimized proof and formula emitted by DRAT-trim. For ER LFSC proofs, we first use drat2er to translate the optimized DRAT proof into an ER proof, which is then sent to the ER LFSC pipeline. The result of each pipeline is an LFSC proof in the corresponding proof system, which can be checked with the corresponding signature (see Section 3) using the LFSC proof checker. Note that prior to bit-blasting, the input is usually simplified via rewriting and other preprocessing techniques, for which CVC4 currently does not produce proofs. The addition of such proofs is left as future work and orthogonal to incorporating DRAT proofs from the SAT solver back-end, which is the focus of this paper.

## 5 Experiments

We implemented the three approaches described in Section 2.1 in CVC4 using CryptoMiniSat 5.6 [14] as the SAT back-end. We compared them against the resolution-based proof machinery currently employed in CVC4 and evaluated our techniques on all 21125 benchmarks from the quantifier-free bit-vector logic QF\_BV of SMT-LIB [3] with status *unsat* or *unknown*. All experiments were performed on a cluster with Intel Xeon E5-2620v4 CPUs with 2.1GHz and 128GB of memory. We used a time limit of 600 seconds (CPU time) and a memory limit of 32GB for each solver/benchmark pair. For each error or memory-out, we added a penalty of 600 seconds.

Proof System	solve		log		log,prod		log,prod,check	
	#	[s]	#	[s]	#	[s]	#	[s]
Resolution	20480	464k	20396	524k	<b>14217</b>	<b>4400k</b>	13510	4973k
DRAT					14098	4492k	12563	5616k
LRAT	<b>20767</b>	<b>283k</b>	<b>20736</b>	<b>319k</b>	14088	4500k	12877	5370k
ER					14035	4565k	<b>13782</b>	<b>4886k</b>

**Table 1.** Impact of proof logging, production, and checking on # solved problems.

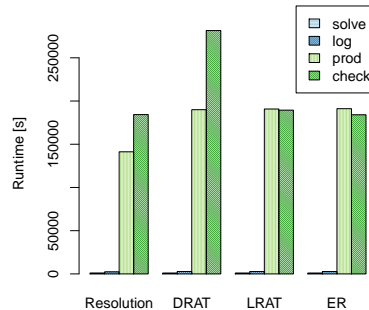
Table 1 shows the results for the Resolution approach with MiniSat, and the DRAT, LRAT and ER approaches with CryptoMiniSat. For each, we ran the following four configurations: proofs disabled (*solve*), proof logging enabled (*log*), proof production enabled (*prod*), and proof checking enabled (*check*). Proof logging records proof-related information but does not produce the actual proof, e.g., when producing DRAT proofs, proof logging stores the DRAT proof from the SAT-solver, which is only translated to LFSC during proof production. In the *solve* configuration, the DRAT-based approaches (using CryptoMiniSat) solve 287 more problems than the Resolution approach (which uses CVC4’s custom version of MiniSat). This indicates that the custom version of MiniSat was a bottleneck for solving. In the *log* configuration, the DRAT-based approaches solve 31 fewer problems than in the *solve* configuration; and in the *prod* configuration the DRAT-based approaches produce proofs for  $\sim 6600$  fewer problems. This indicates that the bottleneck in the DRAT-based approaches is the translation of DRAT to LFSC. For all approaches, about 30% of the solved problems require more than 8GB of memory to produce a proof, showing that proof production can in general be very memory-intensive. Finally, with proof checking enabled, the ER-based approach outperforms all other approaches. Note that in  $\sim 270$  cases, CryptoMiniSat produced a DRAT proof that was rejected by DRAT-trim, which we counted as error. Further, for each *check* configuration, our LFSC checker reported  $\sim 200$  errors, which are not related to our new approach. Both issues need further investigation.

Figure 5 shows the runtime distribution for all approaches and configurations over the commonly proved problems (12539 in total). The runtime overhead of proof production for the DRAT-based approaches is 1.35 times higher compared to resolution. This is due to the fact that we post-process the DRAT-proof prior to translating it to LFSC, which involves writing temporary files and calling external libraries. The proof checking time correlates with the complexity of the side conditions (see Figure 3), where ER clearly outperforms DRAT.

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## 6 Conclusion

We have described three approaches for integrating DRAT proofs in LFSC, which enable us to use off-the-shelf SAT solvers as the SAT back-end for the bit-blasting engine of CVC4 while supporting bit-vector proofs. For future work, we plan to reduce the complexity of the side conditions in the DRAT and LRAT signatures and the proof production overhead in the translation workflows. We also plan to add support for the new signatures in SMTCoq [7], a tool that increases automation in Coq [16] using proofs generated by CVC4. In a more applicative



**Fig. 5.** Runtime distribution on 12539 commonly proved problems.

direction, we plan to explore the potential DRAT proofs in SMT-solvers may have in the proof-carrying code paradigm [12], as well as its recent variant in blockchains, namely proof-carrying smart contracts [5].

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